

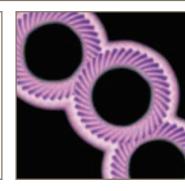


aerospace
climate control
electromechanical
filtration
fluid & gas handling
hydraulics
pneumatics
process control
sealing & shielding





PS Series Gearheads Service Manual





Product Overview

Planetary Gearheads

Our new Generation II Stealth* Series provides higher radial load, increased service life and ease of mounting than comparably sized planetary gearheads. The Stealth Generation II Helical Planetary Gearheads incorporate design enhancements to provide superior performance for the most demanding high performance applications. For larger frame sizes, Parker offers Generation I Stealth* Series gearheads in 142 to





220 mm and NEMA 56 frame sizes. For standard precision applications, the PV Series gearhead combines power and versatility in an economical package available in a wide range of options.

| | . | | 0 | | | | Nominal Continuous | Radial Load | D I J I. | |
|---|-----------------------|----|------------------------------------|-------------------|---------------|-----------------------------|-------------------------------|----------------------------------|---------------------|----|
| | Proc Ser | | Gear Geometry | Performance | Configuration | Frame Size | Torque Nm (in-lb) | N (lbs) | Backlash arc-min | |
| | _ | PS | Helical Planetary | High Precision | In-Line | 60 – 115 mm | 27 - 230 (240 - 2047) | 1650 – 7500 (370 – 1683) | 8 – <3 | 12 |
| | Stealth® | PX | Helical Planetary | Mid Precision | In-Line | 60 – 115 mm NEMA 23 – 42 | 20 – 160 (178 – 1424) | 1550 – 6800 (348 – 1526) | 10 – <6 | 16 |
| | Stealth® | RS | Helical Planetary/ Spiral Bevel | High Precision | Right Angle | 60 – 115 mm | 13 – 220 (115 – 1958) | 1650 – 7500 (370 – 1683) | 14 – <6 | 20 |
| | , | RX | Helical Planetary/ Right Angle | Mid Precision | Right Angle | 60 – 115 mm NEMA 23 – 42 | 10 – 136 (89 – 1210) | 1550 – 6800 (348 – 1526) | 20 – <12 | 24 |
| - | - - - - - | PS | Helical Planetary | High Precision | In-Line | 180 – 220 mm | 294 – 1808 (2616 – 16,091) | 7900 – 58,000 (1775 – 13,020) | 8 – <3 | 30 |
| | Stealth® | PX | Helical Planetary | Mid Precision | In-Line | 142 mm | 220 – 278 (1958 – 2474) | 6000 | 10 – <8 | 34 |
| Č | b S | RS | Helical Planetary/ Spiral Bevel | High Precision | Right Angle | 180 – 220 mm | 141 – 1808 (1255 – 16,091) | 7900 – 58,000 (1775 – 13,020) | 10 – <4 | 36 |
| | | PV | Planetary | Standard | In-Line | 40 – 115 mm NEMA 17 – 42 | 3.5 – 148 | 190 – 10,555 (43 – 2370) | 15 – <12 | 40 |

MultiDrive Gearheads

Stealth® MultiDrive (MD) offers three different output options for true flexibility. MultiDrive models include low-ratio, dual-shaft and hollow-shaft options in a compact, right angle package. With 5 frame sizes and multiple ratios to choose from,you are guaranteed to find a Stealth® MultiDrive to fit your servo motor application.





| D d t | 0 | | | - | Continuous | Radial Load | D l l | |
|-------------------|------------------|----------------|-----------------------------|---------------|--------------------------|-----------------------------|------------------|----|
| Product Series | Gear Geometry | Performance | Configuration | Frame Size | Torque Nm (in-lb) | N (lbs) | Backlash arc-min | |
| RT | Helical | High Precision | Right Angle Hollow Shaft | 90 – 220 mm | 23 - 565 (204 - 5178) | 2800 – 7500 (692 – 1685) | <14 - <6 | 50 |
| RD | Helical | High Precision | Right Angle Double Shaft | 90 – 220 mm | 30 – 150 (266 – 1328 | 2800 – 7500 (692 – 1685) | <14 - <6 | 50 |
| RB | Helical | High Precision | Right Angle Low Ratio | 90 – 220 mm | 35 – 190 (266 – 1682) | 2800 – 7500 (692 – 1685) | <14 - <6 | 50 |

NEMA Gearheads

NEMA gearheads feature a high-efficiency spur gear design, in a light, compact package, and are ideal for applications requiring smooth operation and low starting torque. Ratios from 3:1 to 100:1 are available.



| Product Series | Gear Geometry | Performance | Configuration | Frame Size | Continuous Torque Nm (in-lb) | Radial Load | Backlash arc-min | |
|-------------------|------------------|-------------|---------------|---------------|------------------------------------|------------------------|---------------------|----|
| NE | Spur Gear | Economy | In-Line | NEMA 23 – 42 | 6 – 40 (50 – 350) | 90 – 890 (20 – 200) | 10 – 30 | 58 |

Integral Solution Gearmotors

Stealth' Gearmotors represent the first time a brushless servo motor and a helical planetary gearhead have been integrated into a single product. Previously, engineers needing a gear drive with servo motor were forced to purchase the gearhead and motor separately. Parker Bayside manufactures precision gearheads and gearmotors under one roof.





| Product Series | Gear Geometry | Performance | Configuration | Frame | Continuous Torque Nm (in-lb) | | Backlash arc-min | Page |
|-------------------|-------------------|---------------|---------------|----------------------------------|------------------------------------|----------------------|---------------------|-----------------|
| GM | Helical Planetary | Mid-Precision | In-Line | 60 – 142 mm NEMA 23 – 56 | 3 – 60 | Encoder/ Resolver | < 10 | Consult Factory |
| DX | Planetary | Mid-Precision | In-Line | 6 and 8 inch dia. Wheel Drive | 26 – 48 | Encoder | _ | 62 |

Application Examples

Plastic Bottle Extrusion

The manufacturer of high-performance plastic extrusion equipment needed a drop-in replacement gearhead for an existing worm gearbox used with their motor without having to



alter the design of their machine. The gearhead/motor combination is being used to drive the machine's rollers, controlling the speed at which the plastic is extruded into high-quality plastic sheets. The smoothness of the rollers is critical to the quality of the plastic sheets being produced.

Application Challenges:

High Transmission Error and Velocity Ripple

The customer used worm gearheads to control the rollers. Worm gears exhibit a sliding action of involute gears instead of a rolling action, contributing to the lack of smoothness of the machine rollers. Due to the high transmission error and velocity ripple from the worm drive, the rollers operated at differing speeds. This produced small lines and imperfections on the plastic sheets, rendering it unusable.

High Wear and Low Efficiency

The high level of rubbing (sliding action) between the worm and wheel teeth in the worm gearhead caused a high gear-tooth-wear rate and a lower efficiency (70%) than other major gear types.

Parker SOLUTION:

Stealth PS Gearhead and RT MultiDrive (hollow shaft) Gearhead were used in combination to provide the required 120:1 ratio. The result was high-quality plastics sheets that exceeded the customer's specifications.



The Stealth's all-helical planetary design (HeliCrown Gear Tooth) features extremely high gear tooth accuracy, minimizing transmission error and velocity ripple. The HeliCrown design features extremely high efficiency (95%) while minimizing tooth wear by providing a pure rolling action. Parker's Plasma Nitriding heat-treating process further heightens the gear tooth's wear resistance.

The MultiDrive gearhead features a space-saving bore (hollow shaft) option, eliminating compliance that occurs when coupling a gearhead shaft to the rollers being driven. This solution can be used for a variety of applications, including packaging, food, semiconductor, automotive and medical.

Food/Packaging Automation

A manufacturer of machines for gluing, fill, sealing and diverting food containers for the food-processing industry had a



requirement for the motor and gearhead to be mounted above the food plane. Certain modifications were also needed for the gearhead to make it safe for the food environment, and capable to withstand frequent washdowns.

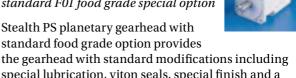
Gearhead Design Considerations:

- Lubrication must be USDA food grade approved in case of incidental contact to food
- · Sealing -must prevent any leaking as well as prevent any ingress of the fluid during washdown
- Finish special FDA-approved finish must be used making it very durable and resistant to chipping, oxidizing or rusting

Output Shaft - stainless steel prevents any rust from developing and contaminating the processing food.

Parker SOLUTION:

Stealth PS planetary gearhead with standard F01 food grade special option



standard food grade option provides the gearhead with standard modifications including special lubrication, viton seals, special finish and a stainless steel output shaft.

Since this food grade modification is a standard option, delivery is only one week over the standard gearhead lead time. (Note: Similar standard modifications exist for vacuum, clean room, high temperature and radiation.)

High-Speed Milling

High-speed milling machines are commonplace in industries such as aerospace and automotive because they allow large structural components to be machined from one piece rather than assembled from



many smaller subcomponents. For a customer that manufactures high-speed milling machines, spindle heads are operating at speeds ranging from 18,000 to 40,000 RPM, so that the cutting is above the resonant frequency of the machine. Because of this, many characteristics become more critical than with their standard machines. The extremely large size of the spindle head also posed problems for the manufacturer in trying to keep it accurately positioned during the milling stage.

Application Challenge:

Low Stiffness

The spindle head was moved rotationally by 2 bull gears, driving a large ring gear. Because of the system characteristics, it was difficult to keep the spindle head absolutely stiff during the milling process. The problems associated with low stiffness are:

- Poor surface finish
- Accuracy errors
- · Excessive tool chatter
- Reduced tool life

Parker SOLUTION:

Two Stealth® PS Helical Planetary Gearheads were used in tandem to create a stiff platform for the spindle machine head. One gearhead, acting as the master, and the other as the slave, were attached to the bull gears to simultaneously turn the ring



gear that positioned the machine head. While the master gearhead moved the ring, the slave was taking up the backlash. In this way, the precision gears allowed for the spindle to be moved accurately, while the two gearhead combination maintained maximum system stiffness.

Parker's Stealth PS gearhead features an all-helical planetary gear design. Helical gears have a much higher tooth-contact ratio and greater face width than straight-spur gears, providing higher loads, smoother tooth engagement and quieter operation. The Stealth's HeliCrown Gear Tooth design provides extremely high gear tooth accuracy, while minimizing tooth wear. Parker Bayside's Plasma Nitriding heat-treating process further heightens the gear tooth's wear resistance.

This solution can also be used in the aerospace and automotive industries.

High-, Mid- and Standard-Precision Planetary Gearheads

Helical planetary technology is superb for low-backlash, high-stiffness and high-accuracy requirements, making the Parker Generation II Stealth® line of helical planetary gearheads ideal for these high-and medium-level performance applications. The introduction of the PV Series gearhead completes the Parker gear family by offering a standard-grade gearhead with the highest radial load capacity available today in a cost-effective solution. Whether you need high-, medium- or standard-grade performance, Parker can match the need. All Parker gearheads are proudly manufactured in the USA in our state-of-the-art facility which, displays the best use of Lean manufacturing practices. For more information go to parkermotion.com.



Generation II Stealth® PS/PX/RS/RX:

Our new Generation II Stealth* series provides higher radial load, increased service life and ease of mounting

The Generation II Stealth* Helical Planetary Gearheads incorporate design enhancements to provide superior performance for the most demanding high performance applications.

Stealth Generation II incorporates dual angular contact bearings providing higher radial load capacities while maintaining high input speeds. Design enhancements also include full complement needle bearings allowing for increased service life and extended warranties. Internal design changes and optimized gearing geometries allow for one oil fill level for any orientation, resulting in shortened part number designation and simplified order placement.

Universal mounting kits provide common mounting kits across multiple product lines to promote quicker deliveries and ease of mounting to any servo motor. Applications that require either high precision (PS/RS Series Gearheads) or mid-range precision (PX/

RX Series Gearheads) utilize the same mounting kit part numbers within the same frame size.

Mounting to any servo motor is as easy as A-B-C (adapter, bushing, collet).

Features & Benefits

- Higher radial load capacity: widely spaced angular contact output bearings
- Increased service life: full complement of planet needle bearings
- Universal mounting kits: quicker deliveries and easier mounting
- High torque and low backlash: helical planetary gearing
- High stiffness: Integral ring gear and rigid sun gear
- Higher gear wear resistance: plasma nitriding heat treating
- PX models are optionally available with flange mounting for easy installation. (Contact factory for flange mount availability for RX models.)



Other Planetary Gearheads:

Generation I Stealth® PS, PX and RS Gearheads

For larger frame sizes, Parker offers Generation I Stealth* Series gearheads in 142 to 220 mm and NEMA 56 frame sizes.

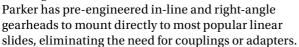
PV Series Precision Gearheads

The PV Series gearhead combines power and versatility in an economical package. It comes in a wide range of options including dimensional output face crossovers to the Parker Bayside PX, Alpha LP, Neugart PLE, Stober PE and Standard NEMA gearheads.

Standard Options for Planetary Gearheads

Gearheads Ready to Mount to Linear Actuators

Most belt driven linear slides need a gearhead to reduce inertia.



Input Shaft Speed Reducer/Speed Increaser for Increased Design Flexibility

Parker gearheads are available with an input-shaft option. The input-shaft option allows more

design flexibility, as options like brakes, encoders, or safety couplings can be used between the motor and the gearhead. This option also allows you to operate the gearhead as a speed increaser.

Mil-Spec Gearheads

Parker has extensive experience in military and aerospace applications. The Stealth Bomber, M1 Tank and the Space Shuttle all use Parker gearheads. Parker's



quality system has been approved by NASA and the US Government to MIL-I-45208A.

Special Environments

Put a Parker gearhead anywhere! Parker can supply gearheads to operate in the harshest environments:



Vacuum - Available as a standard option to 10^{-6} Torr vacuum ratings.

Clean Room - Special gearheads for Class 10,000 clean room applications.

High Temperature - Special lubricants and seals for temperatures up to 250° C.

Radiation - Gearheads customized to operate within radioactive environments.

Food Grade/Washdown - Gearheads customized to operate within food-handling and washdown environments.

Planetary Gearhead Selection Overview

| Proc | luct | Gear | | | | Nominal Continuous Torque | Radial Load | Backlash | |
|--------------------------|------|------------------------------------|-------------------|---------------|-----------------------------|---------------------------------|----------------------------------|----------|----|
| Ser | | Geometry | Performance | Configuration | Frame Size | Nm (in-lb) | N (lbs) | arc-min | |
| _ | PS | Helical Planetary | High Precision | In-Line | 60 – 115 mm | 27 – 230 (240 – 2047) | 1650 – 7500 (370 – 1683) | 8 – <3 | 12 |
| | PX | Helical Planetary | Mid Precision | In-Line | 60 – 115 mm NEMA 23 – 42 | 20 – 160 (178 – 1424) | 1550 – 6800 (348 – 1526) | 10 – <6 | 16 |
| Generation Stealth® | RS | Helical Planetary/ Spiral Bevel | High Precision | Right Angle | 60 – 115 mm | 13 – 220 (115 – 1958) | 1650 – 7500 (370 – 1683) | 14 – <6 | 20 |
| J | RX | Helical Planetary/ Right Angle | Mid Precision | Right Angle | 60 – 115 mm NEMA 23 – 42 | 10 – 136 (89 – 1210) | 1550 – 6800 (348 – 1526) | 20 – <12 | 24 |
| l nc | PS | Helical Planetary | High Precision | In-Line | 180 – 220 mm | 294 – 1808 (2616 – 16,091) | 7900 – 58,000 (1775 – 13,020) | 8 – <3 | 30 |
| Generation I Stealth® | PX | Helical Planetary | Mid Precision | In-Line | 142 mm NEMA 56 | 220 – 278 (1958 – 2474) | 6000 (1347) | 10 – <8 | 34 |
| Ger | RS | Helical Planetary/ Spiral Bevel | High Precision | Right Angle | 180 – 220 mm | 141 – 1808 (1255 – 16,091) | 7900 – 58,000 (1775 – 13,020) | 10 – <4 | 36 |
| | PV | Planetary | Standard | In-Line | 40 – 115 mm NEMA 17 – 42 | 3.5 – 148 | 190 – 10,555 (43 – 2370) | 15 – <12 | 40 |

Helical Planetary Gearhead Features

Parker planetary gearheads incorporate the latest

technology enhancements...

- Latest technology in seals to reduce heat and wear
- Oil lubrication reduces friction and operating temperature, increasing gear life

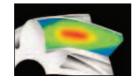
Helical Planetary Design

Helical gears have more tooth contact and greater face width than spur gears. This results in higher loads, smoother tooth engagement, quieter operation and lower backlash.



HeliCrown®

Parker developed the HeliCrown gear tooth to further optimize Stealth's* performance. Since most



vibration occurs at the entry and exit points of a gear tooth, HeliCrown eliminates metal only in these areas, without sacrificing gear strength, producing a quieter and stronger gear.

Plasma Nitriding

Parker's in-house Plasma
Nitriding process results in an ideal gear tooth. The surface is very hard (65 Rc) and the core is strong, but flexible (36 Rc).
The result is a wear-resistant gear tooth that can withstand



heavy shock, ensuring high accuracy for the life of the gearhead.

ServoMount®

Parker's ServoMount design features a balanced input gear supported by a floating bearing. This unique design compensates for motor shaft runout and misalignment, ensuring TRUE alignment of



the input sun gear with the planetary section and allowing input speeds up to 6,000 RPM. ServoMount ensures error-free installation to any motor, in a matter of minutes.





"The Helical Advantage"

Parker planetary gearheads are a superior design with construction integrity to deliver power, speed and accuracy – quietly and efficiently.

Power... 30% more torque than comparably

sized gearheads

Speed... up to 6,000 RPM input speeds **Accuracy...** Less than 3 arc-minutes backlash

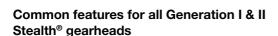
Quiet... Less than 68 dB noise **Efficiency...** Over 97% efficiency

Parker Stealth® planetary gearhead features

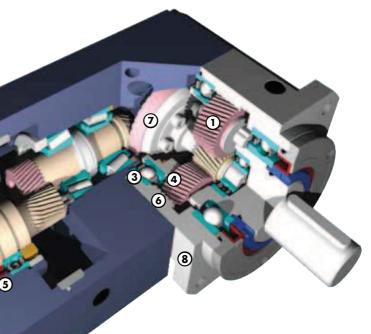
Universal mounting kits offer easier mounting and quick delivery

Features unique to Generation II Stealth® gearheads

- · Widely spaced angular contact bearings provide higher radial load capacity
- · Full compliment of needle bearings for increased service life



- ① **Helical Planetary** Provides smooth, quiet operation, high torque and high accuracy.
- ② ServoMount* Motor-mounting design ensures error-free installation and the balanced pinion allows higher input speeds.
- 3 **Precision Bearings** Provide high speed and high radial and axial load capacity.
- 4 HeliCrown* Parker's proprietary gear tooth geometry ensures quieter operation and higher loads than conventional gears.
- **Sealed Unit** Vition seals and O-Rings provide IP65 protection to prevent leaks and protect against harsh environments.
- Integral Ring Gear Cutting the ring gear directly into the housing allows for larger bearing and planet gears, delivering maximum power and stiffness in a minimum package.



Features unique to Stealth® right-angle gearheads

- Spiral Bevel Gears Deliver high efficiency and high torque in a compact, right angle package.
- **8 Compact Design** Package size is the same regardless of ratio.

Space Tight? Turn Right

For space constrained applications, Parker's RS and RX right-angle gearheads offer as much as a 2X space savings compared to in-line products.

Generation II Stealth® Series PS Generation II Performance Specifications

| D | I lada | D-#- | | S60 | | S90 | | 115 | | 142 |
|---|----------------------------|----------------------|------|-------|-------|------------|--------|------------|------|--------|
| Parameter | Units | Ratio | | en II | | en II | | en II | | n II |
| Nominal Output Torque 1) | N 1 (* 11.) | 3,15,30 | 27 | (239) | 76 | (673) | 172 | (1522) | 300 | (2656) |
| T _{nom r} | Nm (in-lb) | 4,5,7,20,25,40,50,70 | 37 | (327) | 110 | (974) | 230 | (2036) | 430 | (3807) |
| | | 10,100 | 32 | (283) | 93 | (823) | 205 | (1814) | 310 | (2745) |
| Maximum Acceleration Output | " | 3,15,30 | 34 | (300) | 105 | (930) | 225 | (1990) | 450 | (3984) |
| Torque ²⁾ | Nm (in-lb) | 4,5,7,20,25,40,50,70 | 48 | (425) | 123 | (1090) | 285 | (2525) | 645 | (5711) |
| T _{acc r} | | 10,100 | 37 | (325) | 112 | (990) | 240 | (2125) | 465 | (4117) |
| Emergency Stop Output Torque 3 |) | 3,15,30 | 80 | (710) | 260 | (2300) | 600 | (5310) | 1100 | (9739) |
| T _{em r} | Nm (in-lb) | 4,5,7,20,25,40,50,70 | 70 | (620) | 230 | (2035) | 500 | (4425) | 970 | (8588) |
| | | 10,100 | 60 | (530) | 200 | (1770) | 430 | (3805) | 830 | (7349) |
| | | 3 | | 000 | | 500 | | 000 | | 500 |
| | | 4,5 | | 500 | | 000 | | 500 | | 000 |
| Nominal Input Speed Nnom r | RPM | 7,10,15 | | 000 | | 500 | | 000 | | 500 |
| | | 20,25,30 | | 500 | | 000 | | 500 | | 000 |
| | | 40,50 | | 300 | | 100 300 | | 300 200 | | 200 |
| Maximum Input Speed N 4) | RPM | 70,100 3 – 100 | | 200 | | 500 | | 500 | | 000 |
| Maximum Input Speed N _{max r} ⁴⁾ Maximum Radial Load Pr _{max} ^{5,7} | | 3 – 100 | 1650 | (370) | | | | (1685) | | |
| Maximum Axial Load Pa _{max} 6 | N (lbs) | | 2100 | ` ′ | | (810) | | (1530) | | ` ' |
| Service Life | h | | 2100 | (473) | 3000 | 20, | | (1330) | 0000 | (1370) |
| OEIVIGE LIIE | | 3 – 10 | , | <6 | _ | <6 | | <4 | | :4 |
| Standard Backlash 8) | arc-min | 15 – 100 | | <8 | | <8 | | <6 | | <6 |
| | | 3 – 10 | | <4 | | <4 | | <3 | | <3 |
| Low Backlash 8) | arc-min | 15 – 100 | | <6 | | <6 | | <5 | | <5 |
| | | 3 – 10 | | 97 | | 97 | | 97 | | 97 |
| Efficiency at Nominal Torque | % | 15 – 100 | | 94 | | 94 | | 94 | | 94 |
| Noise Level at 3000 RPM 9) | db | 3 – 100 | < | 62 | < | 62 | < | 65 | < | 66 |
| Torsional Stiffness | Nm/arc-min (in-lb/arc-min) | 3 – 100 | 3 | (27) | 12 | (105) | 27 | (240) | 50 | (438) |
| Maximum Allowable Case Temperature | ° C | 3 – 100 | | | | -20 t | o 90 | | | |
| Lubrication | | 3 – 100 | | | Per M | laintena | nce Sc | hedule | | |
| Mounting Position | | 3 – 100 | | | | Aı | าy | | | |
| Direction of Rotation | | 3 – 100 | | | | Same a | s Inpu | t | | |
| Degree of Protection | | | | | | IP | 65 | | | |
| Maximum Waight | ka (lbs) | 3 – 10 | 1.3 | (2.9) | 3.0 | (6.6) | 7.0 | (15.4) | 14.0 | (30.0) |
| Maximum Weight | kg (lbs) | 15 – 100 | 1.7 | (3.7) | 5.0 | (11.0) | 10.0 | (22.0) | 20.0 | (43.0) |
| 4) At a surfact and a like and a | | | | | | | | | | |

¹⁾ At nominal speed Nnom r.

²⁾ Parker MotionSizer sizing software available for free download at parkermotion.com.

³⁾ Maximum of 1000 stops.

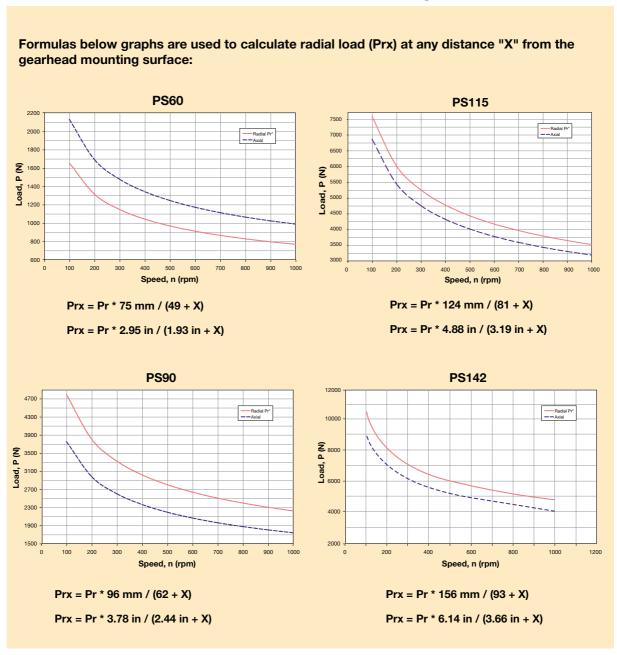
⁴⁾ For intermittent operation.

⁵⁾ Max radial load applied to the center of the shaft at 100 rpm.

⁶⁾ Max axial load at 100 rpm.

⁷⁾ For combined radial and axial load consult factory.
8) Measured at 2% of rated torque.
9) Measure at 1m.

PS Generation II Output Shaft Load Rating

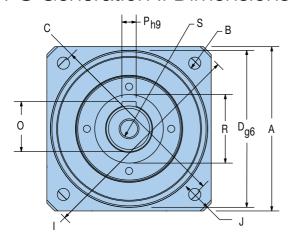


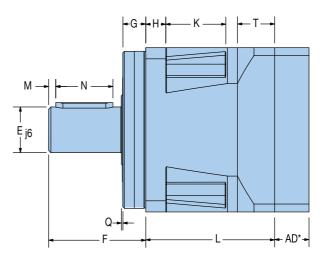
^{*} Radial load applied to center of the shaft.

Generation II Stealth® Series

PS Generation II Dimensions

Free 3D Solid Models and drawings available at parkermotion.com





Metric Frame Sizes

| | , | A | I | В | (| С | l | D | | E | I | F | (| G |
|-------|-----|-------|------|-------|-----|-------|------|-------|------|---------|-----|-------|------|-------|
| _ | | uare | _ | olt | _ | olt | | lot | • | t Shaft | • | | | lot |
| Frame | Fla | nge | Н | ole | CII | rcle | Diar | neter | Diar | neter | Ler | ngth | Thic | kness |
| Size | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in |
| PS60 | 62 | 2.441 | 5.5 | 0.217 | 70 | 2.756 | 50 | 1.969 | 16 | 0.630 | 40 | 1.575 | 11 | 0.433 |
| PS90 | 90 | 3.543 | 6.5 | 0.256 | 100 | 3.937 | 80 | 3.150 | 22 | 0.866 | 52 | 2.047 | 15 | 0.591 |
| PS115 | 115 | 4.528 | 8.5 | 0.335 | 130 | 5.118 | 110 | 4.331 | 32 | 1.260 | 68 | 2.677 | 16 | 0.630 |
| PS142 | 142 | 5.591 | 11.0 | 0.433 | 165 | 6.496 | 130 | 5.118 | 40 | 1.575 | 102 | 4.016 | 20 | 0.787 |

| | ı | н | | I | | J | 1 | K | L | .1 | L | .2 | ı | М |
|-------|------------|-------|-----|---------------|------|-----------------------------|----|-------|----------------------------|-------|------------------------------|-------|------------|-------|
| Frame | HILLONIESS | | | sing neter | | using Recess cess Length | | | Length (3–10 Ratios) | | Length (15–100 Ratios) | | Distance f | |
| Size | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in |
| PS60 | 8 | 0.315 | 80 | 3.150 | 5 | 0.197 | 24 | 0.945 | 59.8 | 2.354 | 94.8 | 3.732 | 2 | 0.079 |
| PS90 | 10 | 0.394 | 116 | 4.567 | 6.5 | 0.256 | 33 | 1.299 | 69.5 | 2.736 | 113 | 4.449 | 3 | 0.118 |
| PS115 | 14 | 0.551 | 152 | 5.984 | 7.5 | 0.295 | 42 | 1.654 | 90.2 | 3.551 | 143.4 | 5.646 | 5 | 0.197 |
| PS142 | 15 | 0.591 | 185 | 7.283 | 10.0 | 0.394 | 45 | 1.772 | 103.7 | 4.083 | 170.7 | 6.720 | 5 | 0.197 |

| | N | | (| 0 | ı | Р | (| Q | R | | s | Т | |
|-------|--------|-------|------|-------------|----|--------|--------|-------|----------|-------|----------------|--------------|-------|
| _ | Keyway | | K | Key | | Keyway | | ulder | Sho | ulder | | Rear Housing | |
| Frame | Length | | He | eight Width | | dth | Height | | Diameter | | Tap & Depth | Thickness | |
| Size | mm | in | mm | in | mm | in | mm | in | mm | in | (end of shaft) | mm | in |
| PS60 | 25 | 0.984 | 18 | 0.709 | 5 | 0.197 | 1 | 0.039 | 22 | 0.866 | M5x8 | 20.3 | 0.799 |
| PS90 | 32 | 1.260 | 24.5 | 0.965 | 6 | 0.236 | 1 | 0.039 | 35 | 1.378 | M8x16 | 20 | 0.787 |
| PS115 | 40 | 1.575 | 35 | 1.378 | 10 | 0.394 | 1.5 | 0.059 | 50 | 1.969 | M12x25 | 26 | 1.024 |
| PS142 | 63 | 2.480 | 43 | 1.693 | 12 | 0.472 | 2.5 | 0.098 | 78 | 3.071 | M16x32 | 31 | 1.220 |

PS Generation II Universal Mounting Kit*

Adapter Length "AD" Dimension

| | Motor Sh | aft Length | Gearhead Adapter Length | | | | |
|------------|-----------|---------------|-------------------------|-------|--|--|--|
| Frame Size | mm | in | mm | in | | | |
| 60 | 16 – 35 | 0.630 - 1.378 | 16.5 | 0.65 | | | |
| | 35.1 – 41 | 1.382 - 1.614 | 22.5 | 0.886 | | | |
| 90 | 20 – 40 | 0.787 – 1.575 | 20 | 0.787 | | | |
| | 40.1 – 48 | 1.579 – 1.890 | 28.5 | 1.122 | | | |
| 115 | 22 - 50 | 0.866 - 1.969 | 24 | 0.945 | | | |
| | 50.1 - 61 | 1.972 - 2.402 | 35 | 1.378 | | | |
| 142 | 26 - 62 | 1.023 - 2.441 | 30 | 1.181 | | | |
| | 62.1 - 82 | 2.445 - 3.228 | 50 | 1.969 | | | |

^{*} Know your motor and need our mounting kit part number? See page 29 or use our Motor Mounting Search Tool on our website at: www.parkermotion.com

PS Generation II Inertia

All moment of inertia values are as reflected at the input of the gearhead

| Ratio | Units* | PS60 | PS90 | PS115 | PS142 |
|---------------------|------------------------|----------|----------|----------|----------|
| 3 | kg-cm ² | 0.2500 | 0.9700 | 3.4000 | 14.8000 |
| 3 | in-lb-sec ² | 0.000221 | 0.000858 | 0.003009 | 0.013098 |
| 4 | kg-cm ² | 0.1700 | 0.6700 | 2.2000 | 9.8000 |
| 4 | in-lb-sec ² | 0.000150 | 0.000593 | 0.001947 | 0.008673 |
| 5 | kg-cm ² | 0.1500 | 0.5100 | 1.7000 | 7.0000 |
| 3 | in-lb-sec ² | 0.000133 | 0.000451 | 0.001505 | 0.006195 |
| 7 | kg-cm ² | 0.1400 | 0.4100 | 1.3000 | 5.3000 |
| 1 | in-lb-sec ² | 0.000124 | 0.000363 | 0.001151 | 0.004691 |
| 10 | kg-cm ² | 0.1400 | 0.3700 | 1.1000 | 4.4000 |
| 10 | in-lb-sec ² | 0.000124 | 0.000327 | 0.000974 | 0.003894 |
| 15 | kg-cm ² | 0.1500 | 0.5200 | 0.1700 | 6.4000 |
| 15 | in-lb-sec ² | 0.150000 | 0.000460 | 0.000150 | 0.005664 |
| 20 | kg-cm ² | 0.1500 | 0.5100 | 1.7000 | 6.4000 |
| 20 | in-lb-sec ² | 0.000133 | 0.000451 | 0.001505 | 0.005664 |
| 25 | kg-cm ² | 0.1500 | 0.5100 | 1.7000 | 6.4000 |
| 20 | in-lb-sec ² | 0.000133 | 0.000451 | 0.001505 | 0.005664 |
| 20 40 50 70 400 | kg-cm ² | 0.1300 | 0.3700 | 1.1000 | 4.2000 |
| 30, 40, 50, 70, 100 | in-lb-sec ² | 0.000115 | 0.000327 | 0.000974 | 0.003717 |

^{*} Note: 1 kg-cm² = 0.000885 in-lb-sec²

Generation II Stealth® Series

Generation II Stealth® How to Order

Choose gearhead series, frame size, ratio, backlash and specify motor, make and model for mounting kit from the charts below and on the following page.

Sizing/Selection Design Assistance

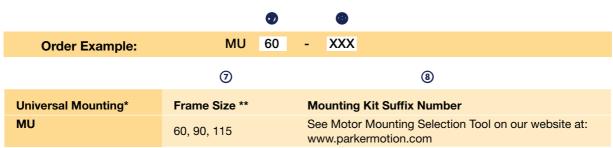
To properly size and select a gearhead for a specific application requires consideration of several interrelated parameters including: speed, continuous torque, repetitive peak torque or acceleration torque, emergency stop torque, duty cycle, ambient temperature and radial and axial shaft load.

The 9 step procedure on pages 72-73 provides a straightforward method of selecting the correct gearhead for your application.

Gearhead Ordering Information

| | | Ü | 2 | (| 3) | 4) | | (5) | 6 | |
|--------|----------------------------|---|------|-----|-----------------------|--|----|------------------|--------|---------------------|
| Or | der Example: | PS | 60 | - 0 | 03 - | XXX | - | S | 2 | |
| 1 | 2 | 3 | | | 4 |) | | (| 5) | 6 |
| Series | Frame Size | Ratio | | s | pecial O _l | otions* | | Backl | ash | GEN 2 Identifier |
| PS | 60, 90, 115, 142 | 003, 004, 005, 007, 0 020, 025, 030, 040, 0 100 | , , | | ίX = Fac | tory issue | ed | | | |
| PX | 60, 90, 115, 23, 34, 42 | 003, 004, 005, 007, 0 020, 025, 030, 040, 0 100 | , , | X. | | tory issue ge Mount | | S = St L = Lo | andard | 2 |
| RS | 60, 90, 115, 142 | 005, 010, 015, 020, 030, 040, 050, 100 | 025, | X | X = Fac | tory issue | ed | L = LC | ΟVV | |
| RX | 60, 90, 115, 23, 34, 42 | 005, 010, 015, 020, 030, 040, 050, 100 | 025, | (C | ontact fa | ctory issue actory for unt Optio | | | | |

^{*} Standard special options include: F01 Food Grade, W01 Washdown, G01 Genl Spacer Plate, L02 No lubricant (standard is oil filled), V01 Vacuum, C01 CleanRoom Class 10,000. Leave blank if no special option required.



Universal Mounting Kit Adapter Length "AD" Dimension

| | Motor St | naft Length | Gearhead Adapter Length | | | | |
|------------|-----------|---------------|-------------------------|-------|--|--|--|
| Frame Size | mm | in | mm | in | | | |
| 60 | 16 – 35 | 0.630 – 1.378 | 16.5 | 0.65 | | | |
| | 35.1 – 41 | 1.382 – 1.614 | 22.5 | 0.886 | | | |
| 90 | 20 – 40 | 0.787 – 1.575 | 20 | 0.787 | | | |
| | 40.1 – 48 | 1.579 – 1.890 | 28.5 | 1.122 | | | |
| 115 | 22 - 50 | 0.866 - 1.969 | 24 | 0.945 | | | |
| | 50.1 - 61 | 1.972 - 2.402 | 35 | 1.378 | | | |
| 142 | 26 - 62 | 1.023 – 2.44 | 30 | 1.181 | | | |
| | 46 - 82 | 1.811 – 3.23 | 50 | 1.969 | | | |

Recommended Parker Motor and Mounting Kit

| | Reco | mmended Servo | Motor | Recommended Stepper Motor | | | | | |
|------------|------------------|-------------------------|--------------|---------------------------|--------------|--------------|--|--|--|
| Frame Size | Motor | Mounting Kit | AD Dimension | Motor | Mounting Kit | AD Dimension | | | |
| 60 or 23 | BE23 SM23 | MU60-033 | 16.5 mm | LV23 HV23 | MU60-005 | 16.5 mm | | | |
| 90 or 34 | MPP092 BE34 | MU90-092 MU90-005 | 20 mm | LV34 HV34 | MU90-005 | 20 mm | | | |
| 115 or 42 | MPP100 MPP115 | MU-115-039 MU115-010 | 24 mm | | | | | | |
| 142 | MPP115 MPP142 | MU142-010 Mu142-146 | 30 mm | | | | | | |

^{*} Common to PS, PX, RS and RX Series Gearheads
**PX/RX23 use MU60, PX/RX34 use MU90, PX/RX42 use MU115

Generation I Stealth® Series

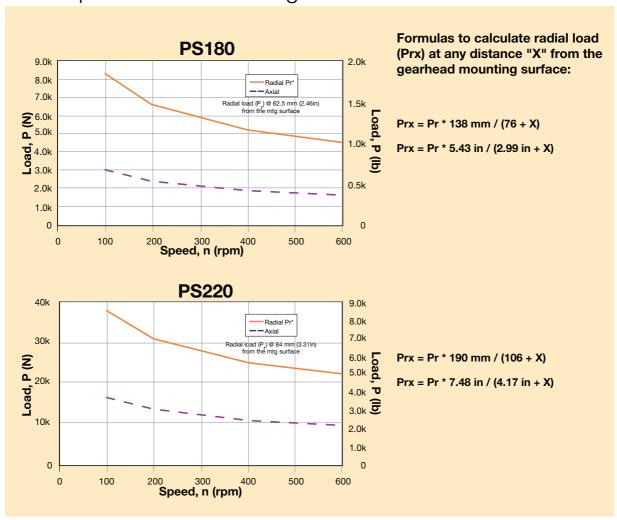
PS Performance Specifications

| Parameter | Units | Ratio | PS | 6180 | PS | 6220 | | |
|--|-------------------------------|-----------------------|-----------------|----------|-----------|-------------|--|--|
| | | 3,4,5,7,10 | 735 | (6500) | 1413 | (12,500) | | |
| Nominal Output Torque T _{nom r} | Nm (in-lb) | 15,20,25, 30,40,50 | 1017 | (9000) | 1808 | (16,000) | | |
| | | 70,100 | 893 | (7900) | 1582 | (14,000) | | |
| Maximum Acceleration Output Torque 1) | Nm (in-lb) | 3,4,5,7,10 70,100 | 972 | (8600) | 1763 | (15,600) | | |
| T _{acc r} | NIII (III-ID) | 15,20,25, 30,40,50 | 1198 | (10,600) | 2011 | (17,800) | | |
| Emergency Stop Output Torque 2) | Nm (in-lb) | 3,4,5,7,10 70,100 | 2237 | (19,800) | 4068 | (36,000) | | |
| T _{em r} | IVIII (III-ID) | 15,20,25, 30,40,50 | 2757 | (24,400) | 4520 | (40,000) | | |
| | | 3,4,5 | 10 | 600 | 12 | 200 | | |
| | | 7,10 | 20 | 000 | 15 | 500 | | |
| Nominal Input Speed N _{nom r} | RPM | 15,20,25, 30,40,50 | 24 | 400 | 1800 | | | |
| | | 70,100 | 28 | 300 | 2100 | | | |
| Maximum Input Speed N _{max r} | RPM | 3 – 100 | | 000 | 2300 4 | | | |
| Standard Backlash 3) | arc-min | 3 – 10 | | 4 | | | | |
| | | 15 – 100 | | 6 | 6 | | | |
| Low Backlash ³⁾ | arc-min | 3 – 10 | | 3 | 3 | | | |
| | | 15 – 100 | | 5 | 5 | | | |
| Efficiency at Nominal Torque | % | 3 – 10 15 – 100 | | 97 94 | 97 | | | |
| Noise Level at: | | 15 - 100 | • | 94 | 94 | | | |
| 2000 RPM ⁴⁾ 3000 RPM ⁴⁾ | db | 3 – 100 | 3 – 100 66 – | | • | 68 — | | |
| Torsional Stiffness | Nm/arc-min (in-lb/arc-min) | 3 – 100 | 110 | (973) | 210 | (1,858) | | |
| Maximum Allowable Case Temperature | ° C | 3 – 100 | | -20 to | 90 | | | |
| Degree of Protection | | | | IP6 | 5 | | | |
| Maximum Weight | kg (lbs) | 3 – 10 | 26 | (57) | 49 | (108) | | |
| a.simani 170.g.it | 1.9 (100) | 15 – 100 | 35 | (77) | 71 | (157) | | |

Parker MotionSizer sizing software available for free download at parkermotion.com.
 Maximum of 1,000 stops
 Measured at 2% of rated torque

⁴⁾ Measured at 1 meter

PS Output Shaft Load Rating

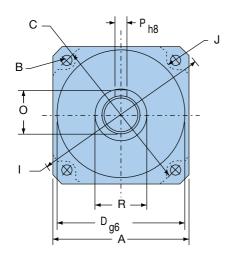


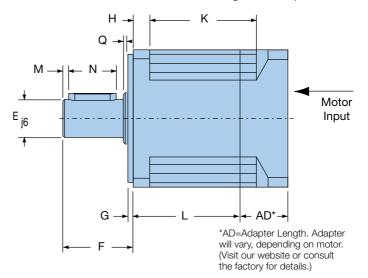
 $^{^{\}ast}$ Radial load applied to center of the shaft.

Generation I Stealth® Series

PS Dimensions

Free 3D Solid Models and drawings available at parkermotion.com





Metric Frame Sizes

| | | Α | | В | | С | | D | | E | | F | | G | | Н | | I | | J |
|-------|------|-------|------|-------|-----|-------|------|-------|------|--------|-----|-------|------|--------|------|--------|------|-------|-----|-------|
| | | | | | | | | | Ou | tput | Ou | tput | | | | | | | | |
| | Sq | uare | В | olt | В | olt | Pi | ilot | Sh | aft | Sh | aft | Pi | ilot | Fla | nge | Ho | using | Hou | using |
| _ | Ela | nge | ш | ole | Ci | rcle | Diar | notor | Dian | notor | Lor | ath | Thic | knace | Thic | kness | Dia | motor | Pο | cess |
| Frame | I Ia | iiige | - '' | OIE | Oil | CIE | Diai | netei | Diai | iletei | Lei | igui | THIC | KIICSS | THIC | KIICSS | Diai | Hetel | ne | CCSS |
| Size | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in | mm | in |
| PS180 | 182 | 7.165 | 13 | 0.512 | 215 | 8.465 | 160 | 6.299 | 55 | 2.165 | 105 | 4.134 | 20 | 0.787 | 16 | 0.630 | 240 | 9.449 | 16 | 0.630 |
| | | | | | | | | | | | | | | | | | | | | |

| | K1 | 1 | K | 2 | L | 1 | L2 | 2 | ı | М | 1 | N | (|) | ı | Р | (| Q | | R |
|---------------|--------------|-------------|----------|-----------|--------|-------------|--------|----------|----------|----------|-----------|------------|-------------|--------------|----------|-----------|----------|----------|------------|-------|
| | | | Rec | ess | | | | | | | | | | | | | | | | |
| | Rece | ess | Lengt | th (for | | | Length | ı (for | Dist | ance | | | | | | | | | | |
| | Length | h (for | ratio | s 15- | Lengt | h (for | ratios | 15- | from | Shaft | Kev | wav | | | Key | way | Sho | ulder | Sho | ulder |
| | | | | | | | | | | | | | | | | | | | | |
| Frame | ratios | 3-10) | 10 | 0) | ratios | 3-10) | 100 | 0) | | nd | • | • | Key I | leight | Wi | dth | He | ight | Diar | neter |
| Frame Size | ratios mm | 3-10) in | 10 mm | 00) in | | 3-10) in | |)) in | | nd | Ler | • | Key I mm | leight in | Wi mm | dth in | He mm | J . | Diar mm | |
| | mm | in | mm | in | mm | in | | in | Ei mm | nd in | Ler mm | ngth in | mm | in | mm | | mm | J | mm | in |

PS InertiaAll moment of inertia values are as reflected at the input of the gearhead

| | | | Frame | Size |
|-------------------|---------------------|------------------------|-------------|------------|
| | Ratio | Units | PS180 | PS220 |
| | | mm | 15.9-35 | 24-48 |
| | 3 to 100 | in | 0.626-1.378 | 0.945-1.89 |
| | 3 | gm-cm-sec ² | 28.6 | _ |
| | . | oz-in-sec ² | 0.397 | _ |
| | 4, 5 | gm-cm-sec ² | 17.6 | 62.6 |
| | 4, 5 | oz-in-sec ² | 0.244 | 0.869 |
| Small Motor Shaft | 7 10 | gm-cm-sec ² | 9.24 | 34.3 |
| Diameter Range | 7, 10 | oz-in-sec ² | 0.128 | 0.476 |
| | 15 | gm-cm-sec ² | 15.8 | 51.0 |
| | 15 | oz-in-sec ² | 0.219 | 0.708 |
| | 20. 25 | gm-cm-sec ² | 16.7 | 53.3 |
| | 20, 25 | oz-in-sec ² | 0.232 | 0.741 |
| | 20 40 50 70 100 | gm-cm-sec ² | 7.450 | 27.1 |
| | 30, 40, 50, 70, 100 | oz-in-sec ² | 0.104 | 0.377 |

| | | | Frame | Size |
|-------------------|---------------------|------------------------|-----------|-----------|
| | Ratio | Units | PS180 | PS220 |
| | 2 to 100 | mm | 35-42 | 48-55 |
| | 3 to 100 | in | 1.38-1.65 | 1.89-2.17 |
| | 3 | gm-cm-sec ² | 37.8 | 111 |
| | S | oz-in-sec ² | 0.526 | 1.54 |
| | 4 5 | gm-cm-sec ² | 25.6 | 72.4 |
| | 4, 5 | oz-in-sec ² | 0.356 | 1.01 |
| Large Motor Shaft | 7.40 | gm-cm-sec ² | 15.8 | 44.1 |
| Diameter Range | 7, 10 | oz-in-sec ² | 0.219 | 0.613 |
| | 15 | gm-cm-sec ² | 23.8 | 60.8 |
| | 15 | oz-in-sec ² | 0.331 | 0.845 |
| | 20, 25 | gm-cm-sec ² | 24.7 | 62.9 |
| | 20, 25 | oz-in-sec ² | 0.344 | 0.874 |
| | 20 40 50 70 400 | gm-cm-sec ² | 14.0 | 37.0 |
| | 30, 40, 50, 70, 100 | oz-in-sec ² | 0.195 | 0.513 |