Parker Series D1FP / D3FP Direct Operated Proportional Directional Control Valve Service Manual

Characteristics

The direct operated control valves D1FP with freely con - figurable control circuit of the nominal size NG06 (CETOP 03) and D3FP of the nominal size NG10 (CETOP 05) shows extremly high dynamics combined with maximum flow. It is the preferred choice for highest accuracy in positioning of hydraulic axis and controlling of pressure and velocity.

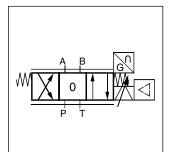
Driven by the patented VCD ${\scriptstyle \circledcirc}$ actuator the D*FP reaches the frequency response of real servovalves. At power-down the spool moves in a defined position. All common input signals are available.

Features

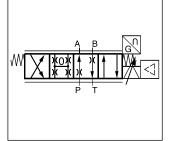
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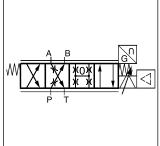
- · Freely configurable supervising control circuit
- Analogue sensor input
- Onboard electronics
- Real servovalve dynamics (-3 dB / 350 Hz at ±5 % input signal)
- Max. tank pressure 350 bar (D1FP), 250 (D3FP) (with external drain port Y)
- Defined spool positioning at power-down optional P-A/B-T or P-B/A-T or center position (for overlapped spools)

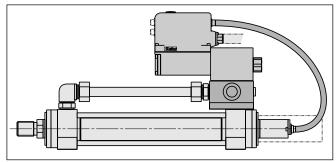




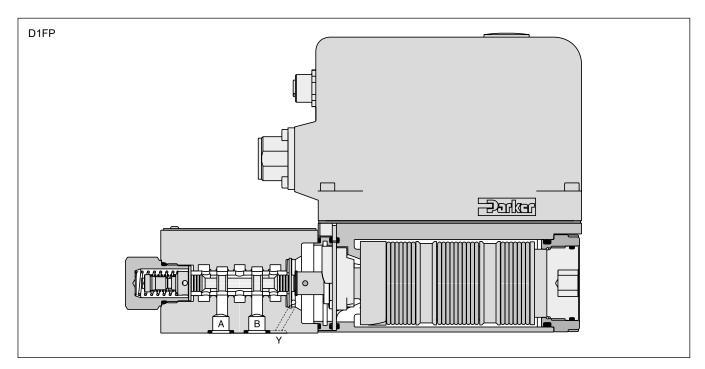








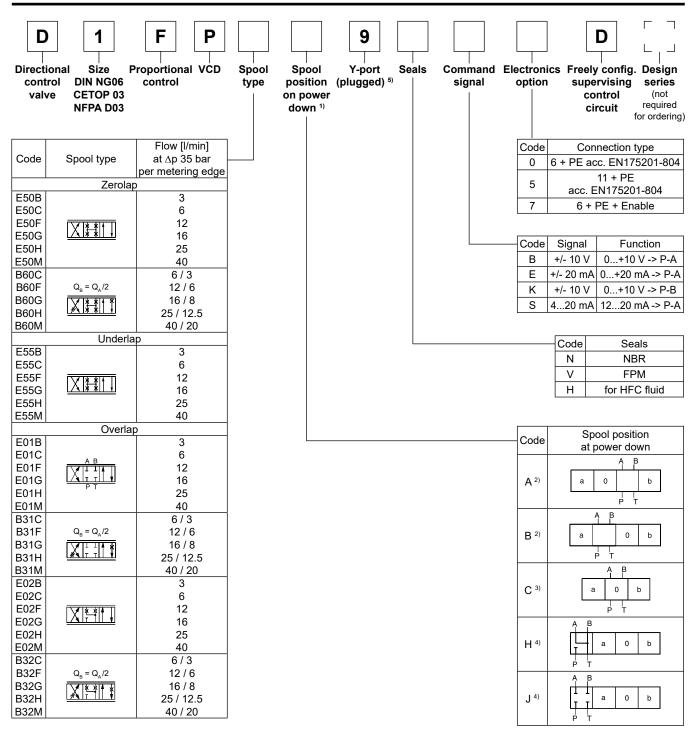
Application example





Ordering Code

Direct Operated Proportional DC Valve Series D*FP*D



Note:

Adapter plate for ISO 4401 to ISO 10372 size 04, Ordering code HAP04WV06-1661

Please order connector separately, see catalogue MSG11-3500/UK, chapter 3 accessories. Parametrizing cable OBE -> RS232, item no. 40982923

¹⁾ On power down the spool moves in a defined position. This cannot be guaranteed in case of single flow path on the control edge A – T resp. B – T with pressure drops above 120 bar or contamination in the hydraulic fluid.

²⁾ Approx. 10 % opening, only zerolap and underlap spools.

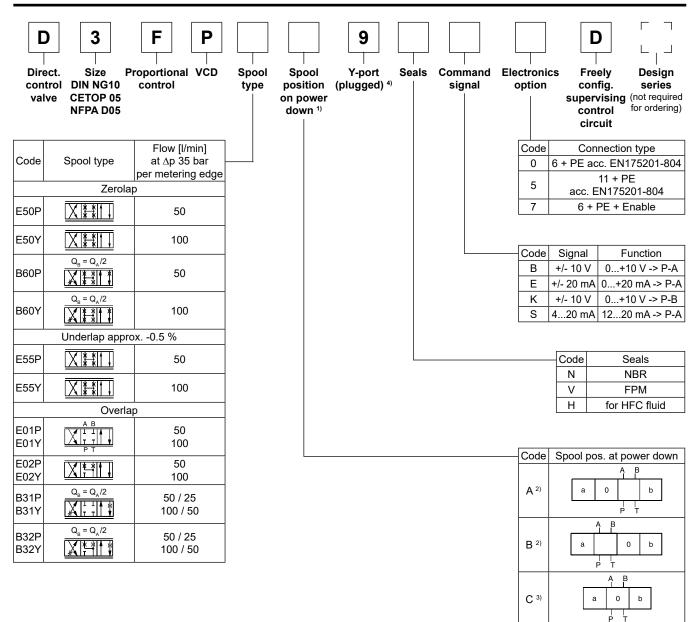
³⁾ Only for overlap spools.

⁴⁾ Not for flow code M (40 l/min).

⁵⁾ Plug in the Y-port needs to be removed at tank pressure >35 bar.



Ordering Code



For regenerative and hybrid function please refer to solutions with sandwich- and adaptor plates "A10-1664 / A10-1665L / H10-1662 / H10-1666L" in catalogue MSG11-3500/UK, chapter 12.

Please order connector separately, see catalogue HY11-3500/UK, chapter 3 accessories.

Parametrizing cable OBE -> RS232, item no. 40982923

²⁾ Approx. 10 % opening, only zerolap spools and underlap spools.

³⁾ Only for overlap spools.

¹⁾ On power down the spool moves in a defined position. This cannot be guaranteed in case of single flow path on the control edge A – T resp. B – T with pressure drops above 120 bar or contamination in the hydraulic fluid.

 $^{^{\}scriptscriptstyle 4)}$ Plug in the Y-port needs to be removed at tank pressure >35 bar.

General						
Design			Direct operated servo proportional DC valve			
Actuation			VCD [®] actuator			
			NG06 / CETOP03 / NFPA D03, NG10 / CETOP05 / NFPA D05			
Mounting interfa	202		DIN 24340 / ISO 4401 / CETOP RP121 / NFPA			
Mounting positi			unrestricted			
		[°C]	-20+50			
MTTF _D value ¹⁾ [years]			5.0 (D1FP), 6.5 (D3FP)			
Weight		[Ky]	10 Sinus 52000 Hz acc. IEC 68-2-6			
Vibration resistance [g]			10 (RMS) Random noise 202000 Hz acc. IEC 68-2-36 15 Shock acc. IEC 68-2-27			
Hydraulic						
Max. operating	pressure	[bar]	Ports P, A, B 350, port T 35 for internal drain, 350 (D1FP), 250 (D3FP) for external drain, port Y 35 ²)			
Fluid			Hydraulic oil according to DIN 51524 535, other on request			
Fluid temperatu			-20+60 (NBR: -25+60)			
Viscosity pern	nitted	[cSt]/mm ² /s]				
recommended [cSt]/mm²/s]						
Filtration			ISO 4406; 18/16/13			
Nominal flow						
at $\Delta p=35$ bar per control edge ³⁾ [l/min]			3 / 6 / 12 / 16 / 25 / 40 (D1FP), 50 / 100 (D3FP)			
			90 at ∆p=350 bar over two control edges (D1FP), 150 (D3FP)			
			< 400 (zerolap spool); < 50 (D1FP overlap spool); < 100 (D3FP overlap spool)			
			set to 23 (D1FP), 19 (D3FP) commande signal (see flow characteristics)			
Static / Dynam						
	at 100 % step 4)	[ms]	< 3.5 (D1FP), < 6 (D3FP)			
Frequency resp	onse					
$(\pm 5 \% \text{ signal})^{4)}$		[Hz]	350 amplitude ratio -3 dB, 350 phase lag -90° (D1FP), 200 amplitude ratio -3 dB,			
			200 phase lag -90° (D3FP)			
Hysteresis						
			< 0.03			
Temperature dr		[%/K]	< 0.025			
Electrical char	racteristics					
Duty ratio		[%]	100			
Protection class			IP65 in accordance with EN 60529 (with correctly mounted plug-in connector)			
Supply voltage/						
Current consun	nption max.		3.5			
Pre-fusing		[A]	4.0 medium lag			
Input signal						
Code B, (K)	Voltage		10010, ripple < 0.01 % eff., surge free, 0+10 V P->A (P->B)			
	Impedance	[kOhm]				
Code E	Current	[mA]	20020, ripple < 0.01 % eff., surge free, 0+20 mA P->A			
	Impedance	[Ohm]				
Code S	Current	[mA]	41220, ripple < 0.01 % eff., surge free, 1220 mA P->A			
			< 3.6 mA = disable, > 3.8 mA = according to NAMUR NE43			
	Impedance	[Ohm]				
Differential inpu	•					
	Code 0	[V]	30 for terminal D and E against PE (terminal G)			
	Code 5	[V]	30 for terminal 4 and 5 against PE (terminal ≟)			
	Code 7	[V]	•			
Enable signal (530, Ri = > 8 kOhm			
Diagnostic sign		[1]				
EMC		[•]	EN 61000-6-2, EN 61000-6-4			
		Code 0/7	6 + PE acc. EN 175201-804			
Electrical conne	ection	Code 0/7 Code 5				
Wiring min.	Code 0/7					
winng min.						
	Code 5		8x1.0 (AWG 16) overall braid shield 50			
Wiring length m						

¹⁾ If valves with onboard electronics are used in safety-related parts of control systems, in case the safety function is requested, the valve electronics voltage supply is to be switched off by a suitable switching element with sufficient reliability.

²⁾ For applications with p_T >35 bar (max. 350 bar) the Y-port has to be connected and the plug in the Y-port has to be removed.

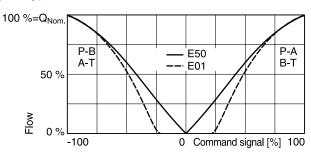
³⁾ Flow rate for different Δp per control edge: $Q_x = Q_{Nom.} \cdot \sqrt{\frac{\Delta p_x}{\Delta p_{Nom.}}}$

⁴⁾ Measured with load (100 bar pressure drop/two control edges).

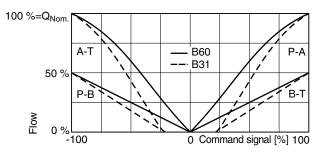


Flow curves

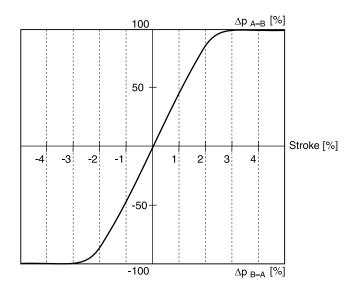
(Overlapped spool set to opening point 23 %) at Δp = 35 bar per metering edge Spool type **E01/E50**



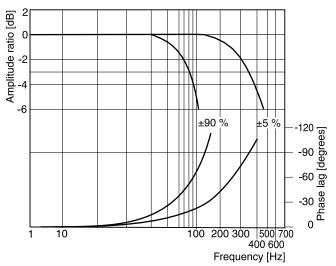
Spool type B31/B60



Pressure gain



Frequency response ±5 % command signal ±90 % command signal

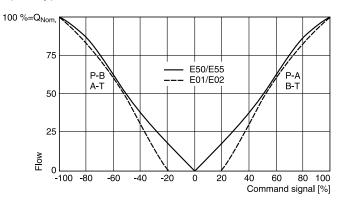


All characteristic curves measured with HLP46 at 50 °C.

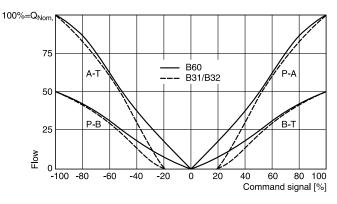


Flow curves

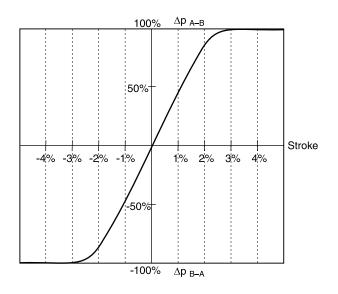
(Overlapped spool set to opening point 19 %) at Δp = 35 bar per metering edge Spool type **E50/E55, E01/E02**



Spool type **B31/B32, B60**

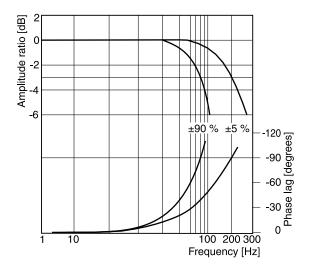


Pressure gain



Frequency response

±5 % command signal ±90 % command signal

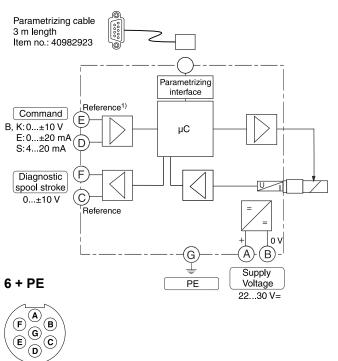


All characteristic curves measured with HLP46 at 50 °C.



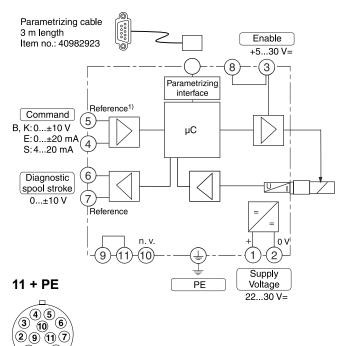
Block Diagrams

Code 0

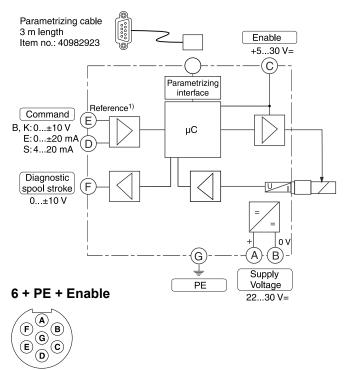


Code 5

1.8

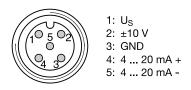


Code 7



¹⁾ Do not connect with supply voltage zero.

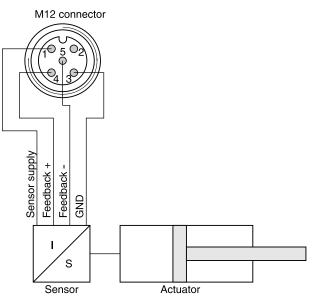
Pin assignment analog sensor, M12 socket



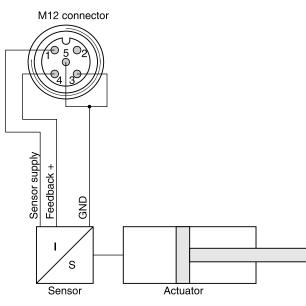
Examples position control

Current 4...12...20 mA contacts at the sensor input

Wiring diagram four-wire



Wiring diagram three-wire

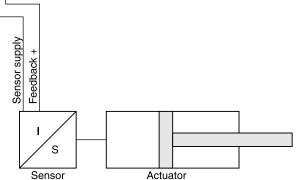


The earth connection is achieved via the shilding.

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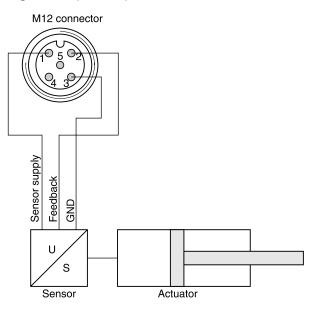
Parker

M12 connector



Voltage ±10 V (1...10 V)

Wiring diagram two-wire



Parker Hannifin Corporation

ProPxD interface program

The ProPxD software allows quick and easy setting of the digital valve electronics. Individual parameters as well as complete settings can be viewed, changed and saved via the comfortable user interface. Parameter sets saved in the non-volatile memory can be loaded to other valves of the same type or printed out for documentation purposes.

The PC software can be downloaded free of charge at www.parker.com/isde – see page "Support" or directly at www.parker.com/propxd.

Features

- Comfortable editing of valve parameters configuration
 of the controller
- · Saving and loading of customized parameter sets
- Executable with all Windows[®] operating systems from Windows[®] XP upwards
- Simple communication between PC and valve electronics via serial interface RS232C

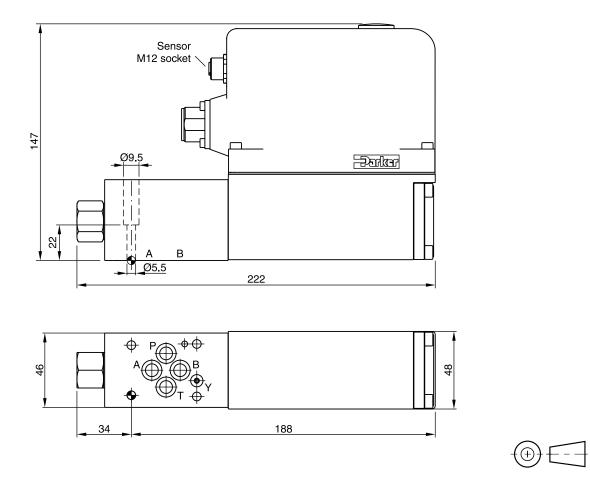
The valve electronics cannot be connected to a PC with a standard USB cable – this can result in damages of PC and/or valve electronics.

The parametrizing cable may be ordered under item no. 40982923.

Par	ker Hanni	fin ProPx	D						>
ile	<u>O</u> ptions	<u>D</u> iagnos	tics	Specials	s <u>H</u> elp 🕻	?			
	expe	ert		D*1FP	"D" Param.]			
DQ			PC			Modul	1	Mandala and an	
PC settings		No.			Module		Module settings		
Туре		J9	1000	relay time out off range min supply voltage [ms]		m I	Type no modul		
D*1FP "D"			_	J12	768	error handling			no modul
			J16	0	4-20mA diagnostics invert		-	Design series	
			E17	1	command signal input (see installation manual)				
Valve			E19	0	command cable break detection (only 420mA)			Version	
vaive			P1	0.0	zero adjustment [%]		2222		
				P11	0	command signal inversion			Valve
	defa	ult		P3	100.0	MAX A-channel [%]			Y GIVE
			P4	100.0	MAX B-channel [%]		-		
			P7	0.0	MIN A-channel [%]		2222		
			P8	0.0	MIN B-channel [%]				
		K17	0.000	zero adjust pilot		-			
			H1	0.00	ctrl loop2 P gain				
				H2	100.00	ctrl loop2 P limit		-	
			H17	117 0.00 ctrl loop2 Integral gain			Parko		
Input			H18	200.00	ctrl loop2 Integral window		-		
Upper limit 28.00	Upper limit 28.00	- 11	H19	100.00	ctrl loop2 Integral limit		-	Receive all	
			H20	0.000	ctrl loop2 fdb mainstage zero correction			Ventil >> PC	
Lower limit	er limit 17.00	H21	0	ctrl loop2 fdb selection					
		I	H22	100.00	ctrl loop2 fdb factor / polarity			Send all	
r h			- 1	H23	0	ctrl loop2 fdb cable break			PC >> Ventil
17				H24	0	ctrl loop2 open / closed loop			save parameter
J8 =	10 -	18.00	- 1	H25	0	ctrl loop2 D Input ringbuffer			
	0 - [18.00		H26	0.00	ctrl loop2 D gain			[
Update list			H27	0.00	ctrl loop2 DT1			Send parameter	
			H28	0.00	ctrl loop2 D limit		-	Default	
_									



D1FP*D



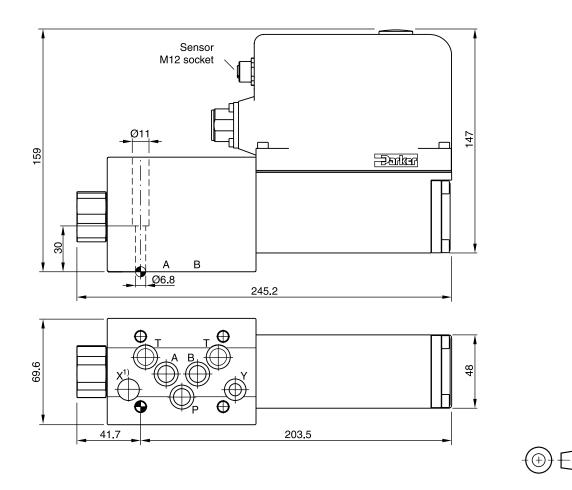
Surface finish	🗦 🛄 Kit	E F	5-7	🔿 Kit
R _{max} 6.3	BK375	4x M5x30 ISO 4762-12.9	7.6 Nm ±15 %	NBR: SK-D1FP FPM: SK-D1FP-V HFC: SK-D1FP-H

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Dimensions

D3FP*D



Surface finish	🖯 🗔 Kit	E F	27	🔿 Kit
R _{max} 6.3 F 0.01/100	BK385	4x M6x40 ISO 4762-12.9	13.2 Nm ±15 %	NBR: SK-D3FP FPM: SK-D3FP-V HFC: SK-D3FP-H

